

Efficient and cost effective method to reduce damaging motor bearing currents in big inverter drive systems

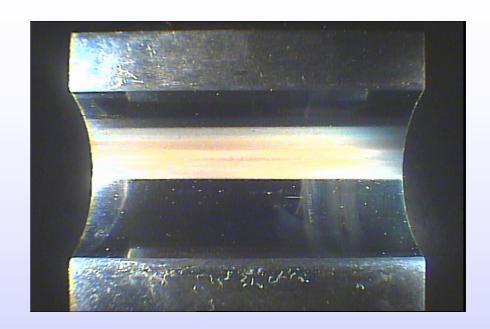


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#### The phenomenon

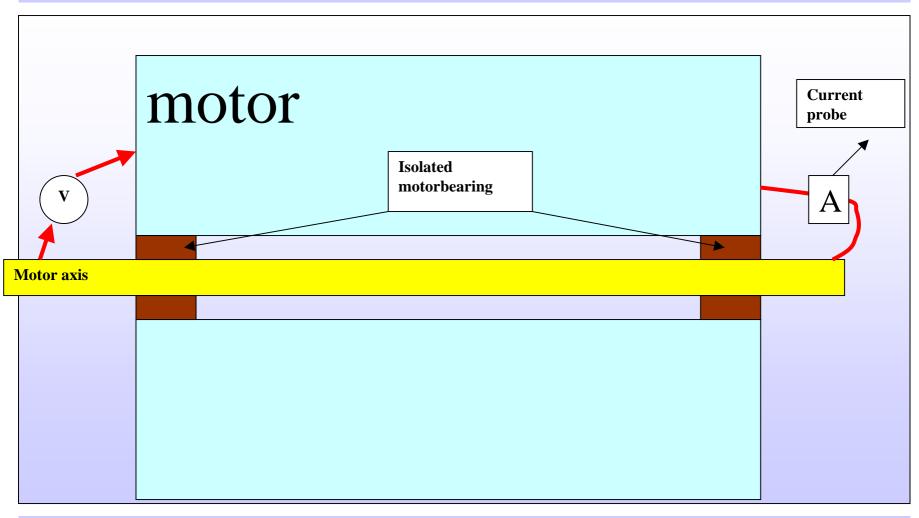




Motor bearing damages

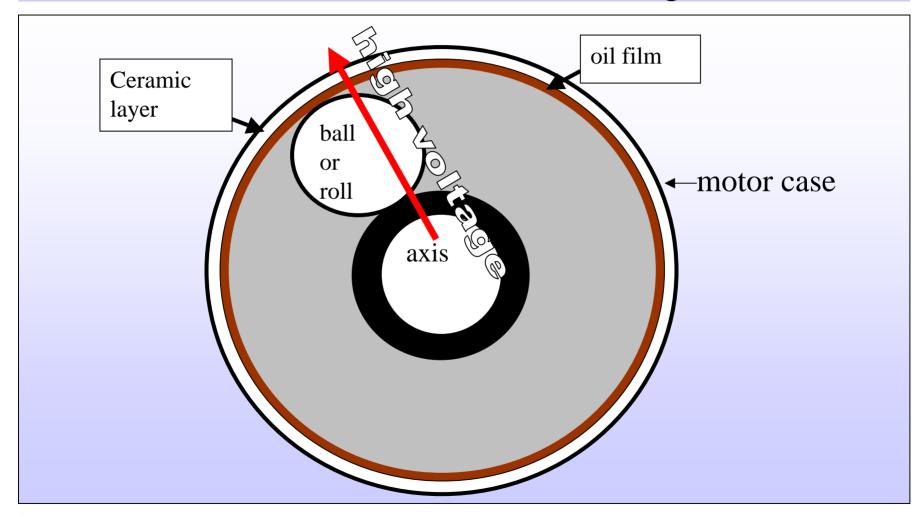


how can you measure the voltage across a bearing?



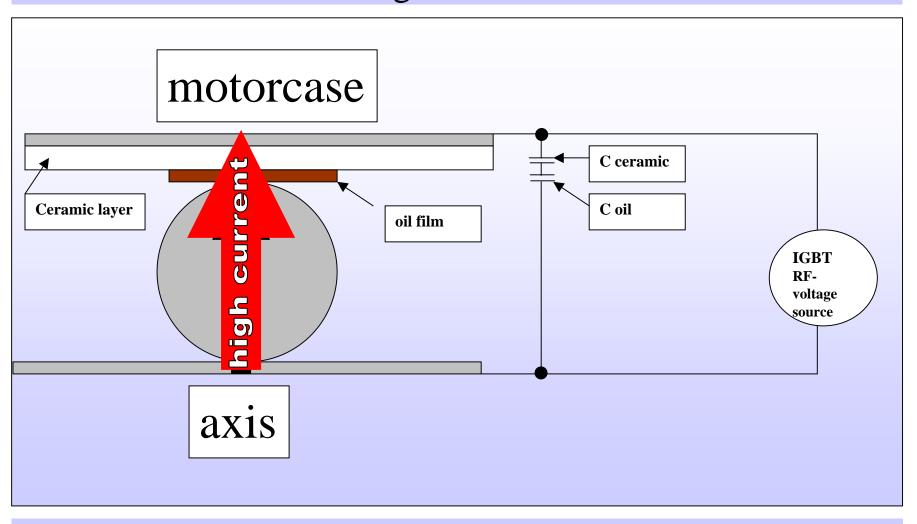


## Effect even on Isolated bearings



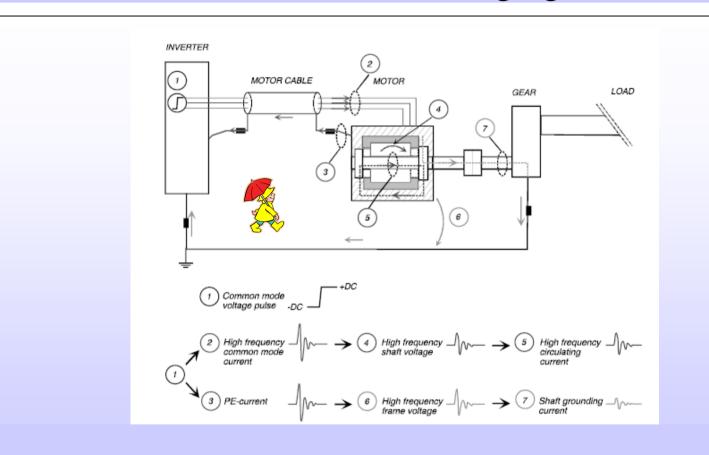


# Ceramic bearing and oil film short cut





#### How can we avoid these damaging currents?





#### A view inside the motor

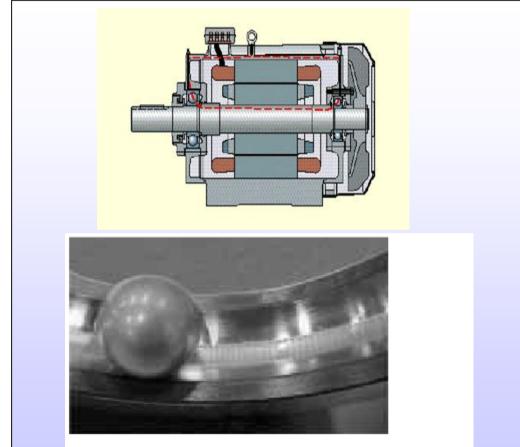
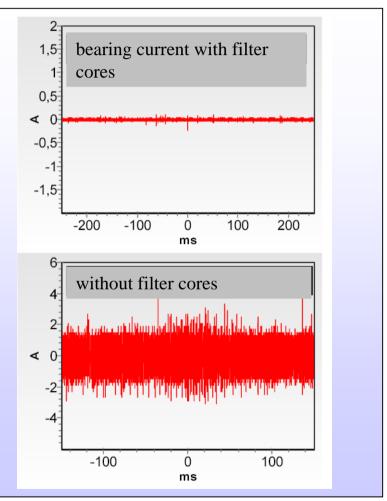
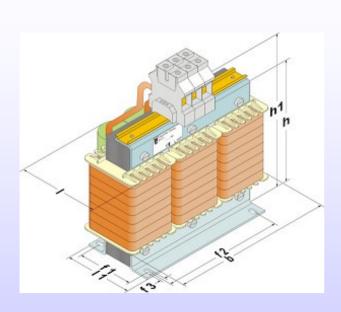


Figure 1: Bearing currents can cause "bearing fluting", a rhythmic pattern on the bearing's races.





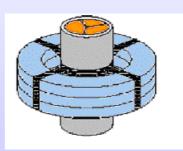
### Different solutions are possible



3-phase motor filter



pot cores



Cool Blue® -cores

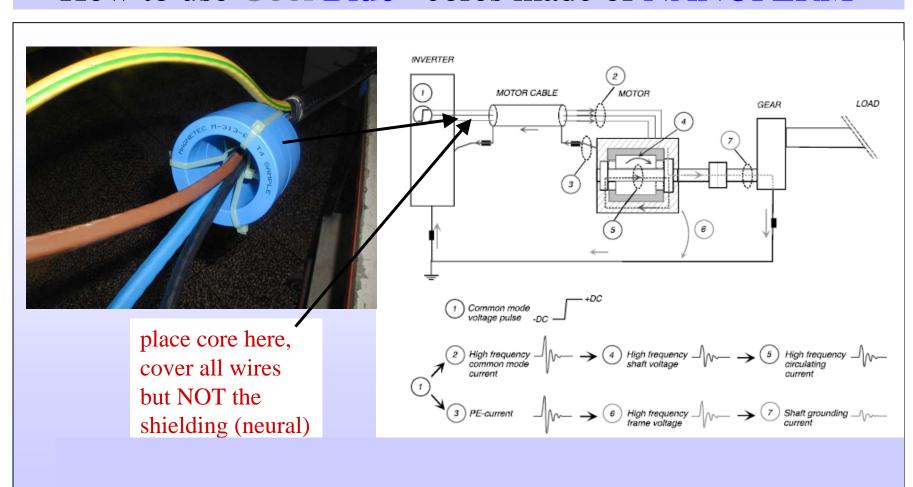


# Why do Cool Blue® provide the best solution?

- low to no noise operation
- low leakage field
- low loss / cool operation
- small volume
- easy to mount
- can easily be re-tooled
- very good value for the money

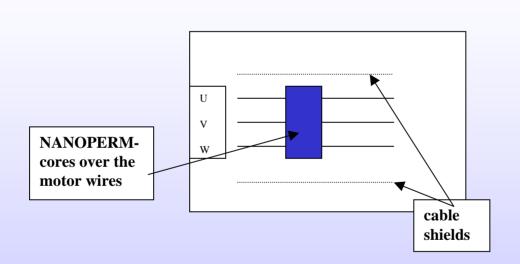


#### How to use Cool Blue® cores made of NANOPERM®





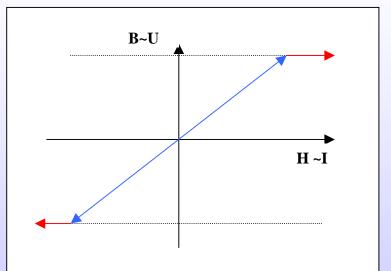
#### How to use Cool Blue® cores made of NANOPERM®



Cores operate as a common mode choke when being put over all motor cables



# How to derive the right Setup of cores?



H ~ I Relate to the sum current L1+L2+L3

B ~ U Relate to the inducted voltage in the core

The amount of cores necessary depends on the sum-bearing current



## Experimental approach



The inner diameter is defined by the cross section of the motor cables

3-4 cores should be mounted together

If the core temperature is  $> 120^{\circ}$ C double the amount of cores

If the temperature is still  $> 120^{\circ}$ C select next bigger core size



## Available <u>round</u> core standard range

Outer diameter	Inner diameter	h	Order no. p/n	max. asymmetric current (sum-current Peak)
80 mm	63	30	M-113	6 A
100	80	30	M-114	8 A
130	100	30	M-115	9 A
160	130	30	M-116	12 A
200	175	30	M-117	16 A
300	250	30	M-205	23 A

- More core types are available on request
- 4 pieces are typically necessary



# Available oval core standard range

Outer diameter	Inner diameter	h	Order no.	max. asymmetric current (sum-current Peak)
80 mm	63	30	M-283	6 A
100	80	30	M-284	8 A
130	100	20	M-142	9 A
160	130	30	M-116	12 A
240	200	30	M-111	19 A
300	250	30	M-248	23 A

- More core types are available on request
- 4 pieces are typically necessary



Motor bearing currents occur not only in Mega Watt – drives!

In MW-drives the switching frequencies are at around 1 kHz

In kW-drives the switiching frequencies are in the 10 kHz range!

This causes motor bearing problems, too!



#### Conclusion

Cool Blue® cores can increase motor bearing's lifetime up to factors compared to the actual standard.

#### Example:

A standstill in a paper factory for replacing the motor bearing costs about 10k€per hour.

The investment of some 100 €is a worth while maintenance measure - it will double the bearing's lifetime!